

Table S1: Summary findings from the reviewed studies.

| Studies | Assessment methods | Sensors | Work Activities | Participants | Measured variables | Key findings | Sensor attachment |
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| Marras WS, et al. Farrag A, et al. Granata KP, et al. Marras W (1992), et al. Marras W (2000), et al. [16,18,19,21,22] | OLBD Risk Model | LMM | MMH activities | | <ul style="list-style-type: none"> Spinal acceleration Angular velocity Magnetic field strength Orientation in the three planes of motion | The system is effective in quantifying trunk kinematic data and identifying the risk level associated with the job | Back |
| Cassisi JE, et al. Elfving B, et al. Peach JP, et al. Ng JK-F, et al. Lloyd DG, et al. [28-31,67] | EMG Assisted Models | sEMG | Various movements including MMH activities | | <ul style="list-style-type: none"> Muscle forces | EMG signals can be used as objective indicators of low back pain cases. Body parts moments can be quantified using EMG-assisted models | Various body parts |
| Cabeças JM. [33] | Strain Index | sEMG | 40 different cleaning activities | 20 cleaning operators | <ul style="list-style-type: none"> Exertion level Exertion frequency Exertion duration | The EMG data could be used as alternative to observational methods to assess the exertion | Right and left wrist flexor and extensor muscles |

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| | | | | | | intensity, frequency, and duration | |
| Giannini P, et al. [36] | NIOSH Lifting Equation | <ul style="list-style-type: none"> • 17 IMUs (Xsens) • 17 IMUs (Noitom) • A custom 11-IMU system | Lifting activities | | <ul style="list-style-type: none"> • Horizontal distance, vertical location, vertical displacement, asymmetry angle, frequency | The system could be used to obtain kinematic and muscles activities data to use in the assessment of MMH activities using the various the listed ergonomic assessment methods. | Head, sternum, shoulder blades, upper arms, lower arms, hands, pelvis, upper legs, lower legs, and foots |
| | Snook & Ciriello | | Pushing/Pulling | | <ul style="list-style-type: none"> • Handle height, covered distance, pushing or pulling frequency | | |
| | REBA | Repetitive high frequency actions | <ul style="list-style-type: none"> • Head flexion/extension • Lateral bending and right/left rotation • Trunk flexion and extension • Knee flexion/extension • Shoulder flexion/raising • Upper arm abduction • Elbow | | Upper arms, lower arms, upper legs, lower legs, pelvis, head and T1 vertebra | | |

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| | | | | | flexion · Wrist flexion/ bending/twisting · Activity frequency | | |
| | Strain Index | Custom EMG system | MMH activities | | · Intensity of exertion · Duration of exertion · frequency of exertion · Wrist posture | | Right/left wrists |
| | Strain Index | Shimmer3 EMG | | | | | |
| Mudiyanselage SE, et al. [37] | NIOSH Lifting Equation | 2 sEMG (Noraxon) | Lifting activities | 1 male | · Thoracic muscles electrical impulses | The developed system could be used to provide insights regarding the ergonomic hazards according to NIOSH Lifting Equation | Upper back muscles (i.e., Thoracic) |
| Peppoloni L, et al. [41] | RULA | 3 IMUs | Grocery cashier | 10 (7 males and 3 females) | · Upper arm flexion · Forearm flexion and pronation/supination · Wrist flexion and abduction · Task frequency · Wrist flexion · Work speed | The system performs an online score computation according to RULA and SI scoring methods | Upper arm, forearm and back of the hand |

| | Strain Index | 8-channel sEMG | | | <ul style="list-style-type: none"> · # of exertion/min · Duration of exertions · Force exertion | | Forearm |
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| Battini D, et al. [42] | RULA, OCRA, OWAS, NIOSH LI | 17 IGS-180i IMUs | MMH tasks at two warehouses | | <ul style="list-style-type: none"> · Upper extremity inclination angles · Task duration · Task frequency · Right and left hands positions (vertically and horizontally) | The developed system enables for the postural assessment using the various ergonomic assessment tools. Some errors were observed such as the evaluation of the head, neck and trunk position | Full body motion capture system |
| Schall MC, et al. [43] | OLBD Risk Model* | 2 series SXT IMUs vs. LMM | Material handling task | 36 males | <ul style="list-style-type: none"> · Spinal acceleration · Angular velocity · Magnetic field strength · Orientation in the three planes of motion | Outcomes obtained from methods used IMUs worn at the sternum and L5/S1 body segments were more equivalent to the LMM data than methods | The sternum and L5/S1 body segment |

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| | | | | | | that computed torso motion only from the IMU worn at the sternum | |
| Schall Jr MC, et al. [44] | (NIOSH, WA L&I, ACGIH, Ohio BWC, Snook, and LiFFT)* | One wGT3X-BT PA accelerometer compared to 3 IMUs ArduIMU v3 | Registered nurse activities | 36 females | · Activity frequency and duration | Limited agreement between the IMUs PA measurements and the wGT3X-BT waist-worn PA measurements. Sensor locations significantly influence the PA measurements | IMUs: upper arms and trunk; PA: waist |
| Valero E, et al. [45] | ATBAN | 7 IMUs | Construction activities | | · Torso bending angles · Leg flexion angles · Right and left hands positions (vertically and horizontally) | The proposed system could be used to detect unsafe body postures based on measurements of motion data from the IMUs | Upper arms, forearms, shins, and lower back |

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| Valero E, et al. [46] | ISO 11226 | 8 IMUs | Construction MMH tasks | 6 male students | <ul style="list-style-type: none"> · Torso inclination · Knee flexion · Kneeling · Arm elevation | The system correctly discriminates between various body postures and classify those at increased risk of OLBD based on ISO 11226 | Upper/lower back, arms and upper/lower legs |
| Yan X, et al. [48] | ISO 11226 | 2 IMUs | Construction activities | | <ul style="list-style-type: none"> · Head, neck, and back inclination angles | The system could be used to provide real-time feedback and warning about the awkward neck and trunk postures | Head and lower back |
| Chen J, et al. [49] | (NIOSH, WA L&I, ACGIH, Ohio BWC, Snook, LiFFT, RULA)* | 17 IMU (Noitom) | Construction MMH tasks | 4 graduate students | <ul style="list-style-type: none"> · Overhead and forward hand reaching · Torso forward bending · Kneeling and squatting · Neck bending · Task duration | The system can accurately identify awkward body postures in construction operation | Pelvis, head, both scapula, upper arms, forearms, sternum, hands, thighs, shanks, and feet |

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| <p>Hischke M, et al. [50]</p> | <p>(RULA, OCRA, OWAS)*</p> | <p>17 IMUs (Xsens)</p> | <p>MMH activities</p> | <p>30 males</p> | <ul style="list-style-type: none"> · Torso flexion and extension · Time spent in each posture | <p>Three configurations of IMU sensors were used to determine the trunk inclination angles. Trunk measurements obtained from the IMU attached to the sternum were the most comparable to those obtained from the IMU on the sternum relative to the IMU on the sacrum</p> | <p>Pelvis, head, both scapula, upper arms, forearms, sternum, hands, thighs, shanks, and feet</p> |
| <p>Brents C, et al. [51]</p> | <p>(RULA, OCRA, OWAS)*</p> | <p>17 IMUs (Xsens)</p> | <p>MMH activities</p> | <p>5 males</p> | <ul style="list-style-type: none"> · Torso flexion and extension · Time spent in each posture | <p>The system could be used to characterize low back angular displacement during keg lifting from different vertical heights</p> | <p>Pelvis, head, both scapula, upper arms, forearms, sternum, hands, thighs, shanks, and feet</p> |

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| Barim MS, et al. [52] | ACGIH TLV for Lifting | 5 IMUs (Kinetic) | MMH activities | 10 (5 males, 5 females) | <ul style="list-style-type: none"> Hand location in the 12 ACGIH TLV lifting zones Trunk inclination angle Task duration | Accurate measurements of the trunk inclination angle and task duration. The mean measurement errors for the horizontal and vertical hand location were 6.5 and 33 cm, respectively | Upper back, left upper arm, right and left wrist, and left thigh |
| Barim MS, et al. [53] | ACGIH TLV for Lifting | 5 IMUs (Kinetic) | MMH activities | 10 (5 males, 5 females) | <ul style="list-style-type: none"> Hand location in the 12 ACGIH TLV lifting zones Trunk inclination angle Task duration | The mean measurement errors for the horizontal and vertical hand location reduced to 2.2 and 14 cm, respectively | Upper back, left upper arm, right and left wrist, and left thigh |
| Beravs T, et al. [54] | RULA, REBA, and OWAS* | 4 IMUs | Lower limb exoskeletons or general human movement | 1 | <ul style="list-style-type: none"> Angles of hip, knee, and ankle | Measured body joint angles with a median absolute error of up to 5 degrees | Trunk, thigh, shank, and foot |

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| Conforti I, et al. [55] | RULA, REBA, and OWAS* | 8 IMUs (Xsens) | Lifting/releasing load tasks | 26 | <ul style="list-style-type: none"> RoM of the lumbosacral, left and right knee, and left and right ankle joint angles | THE IMU system could be used to distinguish between the correct and incorrect lifting/releasing loads | Sternum body, pelvis, mid-thighs, mid-shanks, and instep of the feet |
| Porta M, et al. [57] | (NIOSH, WA L&I, ACGIH, Ohio BWC, Snook, and LiFFT)* | Up to 17 IMUs (Xsens) | MMH activities | 10 (5 males and 5 females) | <ul style="list-style-type: none"> Activity type Duration Frequency | A single IMU can be used to successfully classify the activity type, duration, and frequency | Head, sternum, pelvis, scapulae, the upper and lower arms, hands, thighs, shanks, and feet |
| Faber G, et al. [61] | A top-down inverse dynamics model* | 17 IMUs (Xsens) + force shoes | Lifting/carrying tasks | 16 (8 males, 8 females) | <ul style="list-style-type: none"> Hand forces during lifting | The proposed system measured the hand forces with RMSD of 10-27N. Lower errors were found during lifting as compared to walking and carrying | Pelvis, head, both scapula, upper arms, forearms, sternum, hands, thighs, shanks, and feet |

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| | | | | | | activities | |
| Donisi L, et al. [56] | NIOSH Lifting Equation | A single IMU (Opal System) | Lifting activities | 7 | <ul style="list-style-type: none"> · Pelvis acceleration and angular velocity signals from the IMU were used in machine learning algorithm | The developed system could be used to classify biomechanical risk according to the revised NIOSH lifting equation | Pelvis |
| Faber G, et al. [58] | 3D L5/S1 moments | 17 IMUs (Xsens) + force shoes | Lifting activities | 16 (8 males, 8 females) | <ul style="list-style-type: none"> · 3D L5/S1 moments estimated using top-down and bottom-up models | The top-down model resulted in smaller errors compared to the bottom-up model | Pelvis, head, both scapula, upper arms, forearms, sternum, hands, thighs, shanks, and feet |
| Matijevich ES, et al. [62] | Biomechanical model | 8 IMUs (Xsens) and pressure insoles (Pedar-x) | MMH activities | 10 (7 males and 3 females) | <ul style="list-style-type: none"> · Lumbar moment | A minimum of one IMU sensor attached on the trunk and pressure insoles can predict the lumbar | Feet, shanks, thighs, pelvis, trunk) and pressure insoles placed inside the shoes |

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